

Proof of the main theorem, part I

We want to show that \mathcal{C} admits a stable structure. To do so, we make use of the following result.

Prop. [Lurie, '13] Let \mathcal{C} be an ∞ -cat. Then, \mathcal{C} is stable iff the following conditions are met:

- i) \mathcal{C} is pointed.
- ii) $\forall X \in \text{Ob}(\mathcal{C})$, the pushout

$$\begin{array}{ccc} X & \longrightarrow & * \\ \downarrow & & \downarrow \\ * & \longrightarrow & \Sigma X \end{array}$$

- exists and defines an auto-equivalence $\Sigma: \mathcal{C} \rightarrow \mathcal{C}$;
- iii) every morphism $f: X \rightarrow Y$ admits a cofiber.

This talks: i) & the first part of ii).

Preliminary facts on semi-simplicial sets

The functor $i: \Delta_+ \rightarrow \Delta$ induces a forgetful functor

$$\text{Set} \longleftarrow i^*: \text{Fun}(\Delta_+^{\text{op}}, \text{Set}) \longrightarrow \text{Fun}(\Delta^{\text{op}}, \text{Set}) \longrightarrow \text{ssSet}$$

Through abstract nonsense, i^* admits a left adjoint $i_!$, i.e.

$$\text{ssSet}(i_!(-), -) \cong_{\text{nat}} \text{ssSet}(-, i^*(-))$$

Concretely, $i_!$ is obtained by adjoining degeneracies so that if $(v_0: \dots: v_n) \rightarrow |X|$ is a simplex of the geometric realization of X , then

$$(v_0: \dots: v_n, v_1: \dots: v_n, \dots, v_n: \dots: v_n) \rightarrow |i_!X| = |X|$$

extended trivially, is a simplex of the geometric realization of $i_!X$.

Therefore, we have that

$$i_! \Delta_+^n = \Delta^n, \quad i_!(\partial \Delta_+^n) = \partial \Delta^n, \quad i_!(\Lambda_{n,+}^n) \cong \Lambda_n^n$$

Furthermore, if X is a semi-simplicial set with maps $s_0, s_1: X_n \rightarrow X_{n+1}$ (as constructed in §6), then the resulting simplicial set \widehat{X} has the property that

$$i^* \widehat{X} = X$$

$$\leadsto i^* \text{Fun}(\Delta_+^n, \widehat{X}) \cong \text{Fun}(\Delta_+^n, X)$$

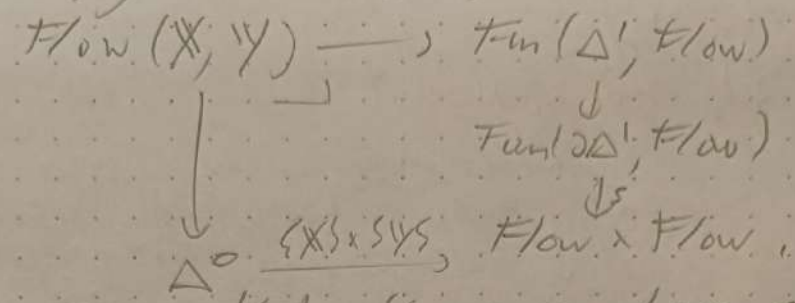
$$\leadsto i^* \text{Fun}(\partial \Delta_+^n, \widehat{X}) \cong \text{Fun}(\partial \Delta_+^n, X)$$

$$\leadsto \pi_n(\widehat{X}, x) = \pi_n(X, x) \quad \text{if } \widehat{X} \text{ is a Kan complex. } \quad \square$$

Moral: Up to homotopy, we can simply work with the semi-simplicial set Flow — everything for the simplicial set will follow automatically.

2. Pointed mapping spaces in Flow

The space $\text{Flow}(X, Y)$ of morphisms $X \rightarrow Y$ is given by the pullback diagram (in Set)



Concretely, this means that the n -simplices of $\text{Flow}(X, Y)$ are given by morphisms

$$\Delta^1 \times \Delta^n \rightarrow \text{Flow}$$

s.t. their restriction to $\partial \Delta^1 \times \Delta^n$ is SX, YS .

Note that $\text{Flow}(X, Y)$ has a favored point in $\mathcal{O}_{X, Y}$, the empty 1-simplex, given as follows. If $\mathcal{O}_X(X) = \emptyset_0$ and $\mathcal{O}_Y(Y) = \emptyset_1$, then $\mathcal{O}_{X, Y}$ has object given by $\vec{p} = (p_0, p_1)$ and

$$\mathcal{O}_{X, Y}(p, q) := \begin{cases} X(p, q) & \text{if } p, q \in \mathcal{O}_X(X) \\ Y(p, q) & \text{if } p, q \in \mathcal{O}_Y(Y) \\ \emptyset & \text{otherwise.} \end{cases}$$

Lemma: The ∞ -cat. Flow is pointed with zero object \emptyset , the empty flow cat. ($\mathcal{O}_\emptyset(\emptyset) = \emptyset$).

Proof: We need to prove that the spaces $\text{Flow}(\emptyset, X)$ and $\text{Flow}(X, \emptyset)$ are contractible $\forall X \in \mathcal{O}_\emptyset(\text{Flow})$, i.e.

$$\pi_n(\text{Flow}(\emptyset, X), \emptyset_X) = \pi_n(\text{Flow}(X, \emptyset), \emptyset_X) = 0 \quad \forall n.$$

For this, it suffices to prove that whenever we have $\partial \Delta^n \rightarrow \text{Flow}$ s.t. one vertex is sent to \emptyset , there is an extension $\Delta^n \rightarrow \text{Flow}$.

However, this is clear: it suffices to associate to the interior of Δ^n the empty n -simplex.

3. Flow is a semi-stable quasi-category (part 2)

We need to show that there is a pair of endofunctors $(\mathcal{E}, \mathcal{E}^{-1})$ of Flow which induces natural equivalences

$$\Omega \text{Flow}(\mathcal{E}^{-1}X, Y) \xleftarrow{\cong} \text{Flow}(X, Y) \xrightarrow{\cong} \Omega \text{Flow}(X, \mathcal{E}Y)$$

where

$$\Sigma \text{Flow}(X, Y) := \text{Fun}(\Delta^1 / \partial \Delta^1, \text{Flow}(X, Y) / \partial_{X, Y})$$

On the level of objects, we set $\Sigma = \Sigma^{-1} = \mathbb{1}$ (this will become clear in the next talk), and we only have one equivalence

$$\text{Flow}(X, Y) \xrightarrow{\sim} \Sigma \text{Flow}(X, Y)$$

$$\Downarrow \quad \Sigma \text{Flow}(X, Y) \longrightarrow \text{Flow}(X, Y)$$

But a morphism $\Sigma X \rightarrow Y$ (where Y is pointed) is specified by a sequence $\Sigma \circ \eta: Y_n \rightarrow Y_{n+1} \rightarrow \dots$ which respects the simplicial id's and s.t.

$$d_0 \circ \eta_n = d_1 \quad \text{and} \quad \eta_n \circ \partial_n = * \quad \leftarrow \text{map that sends everything to the special point of } Y$$

Such maps exist.

Proof: We need to construct

$$\begin{aligned} \eta_n: \text{Fun}_{X, Y}(\Delta^1 \otimes \Delta^n, \text{Flow}) &\longrightarrow \text{Fun}_{X, Y}(\Delta^1 \otimes \Delta^{n+1}, \text{Flow}) \\ &\hookrightarrow \text{Flow}_{\Delta^1 \otimes \Delta^n} = \Sigma X, Y \end{aligned}$$

Let's start with $n=0$. Then, an element on the right is a square!

$$\begin{array}{ccc} X & \xrightarrow{\partial_{X, Y}} & Y \\ \Sigma X \downarrow & \begin{array}{c} M' \\ \xrightarrow{\partial_{X, Y}} \end{array} & \downarrow \Sigma Y \\ X & \xrightarrow{\partial_{X, Y}} & Y \end{array}$$

We decompose this square in 2 2-simplices and construct two maps $\text{Fun}(\Delta^1, \text{Flow}) \rightarrow \text{Fun}(\Delta^2, \text{Flow})$ which match along an edge.

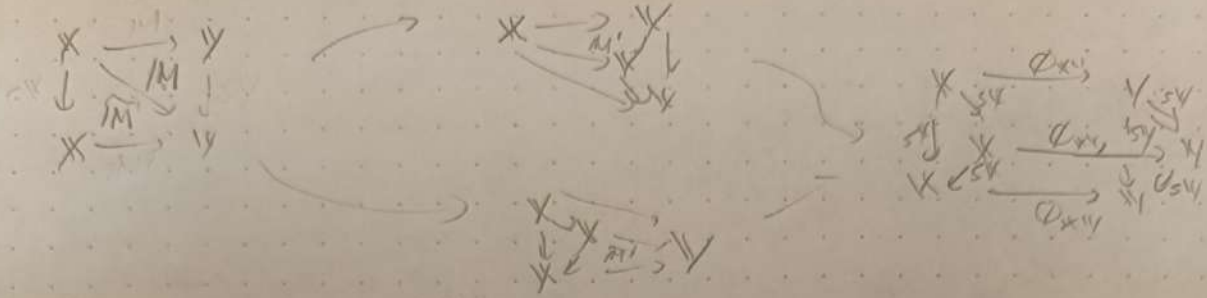
We do as above, where $\partial_1(M') = \partial_1(X) \hookrightarrow \partial_1(Y) \hookrightarrow \partial_1(M)$ and

$$M'(i, j) := \begin{cases} M'(i, j) & \text{if } i \in \partial_1, j \in \partial_2 \\ \emptyset & \text{if } i \in \partial_0, j \in \partial_0 \\ \Sigma Y(i, j) & \text{if } i \in \partial_1, j \in \partial_2 \\ X(i, j) & \text{if } i, j \in \partial_0 \\ Y(i, j) & \text{if } i, j \in \partial_0 \text{ or } i, j \in \partial_2 \end{cases}$$

M'' is defined similarly, but $\partial_1 = \partial_0(X)$ instead.

For general n , it suffices to divide $\Delta^1 \otimes \Delta^n$ in $n+1$ $(n+1)$ -simplices and $\Delta^1 \otimes \Delta^{n+1}$ in $n+2$ $(n+2)$ -simplices and use a similar trick. For example:

(n=1)



We set the identities $d_0 \sigma_n = d_1 \sigma_n$ from our relabeling, which associate to each dim. face an output simplex.